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Wearable microneedle-based electrochemical aptamer biosensing for precision dosing of drugs with narrow therapeutic windows

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Therapeutic drug monitoring is essential for dosing pharmaceuticals with narrow therapeutic windows. Nevertheless, standard methods are imprecise and involve invasive/resource-intensive procedures with long turnaround times. Overcoming these limitations, we present a microneedle-based electrochemical aptamer biosensing patch (μ NEAB-patch) that minimally invasively probes the interstitial fluid (ISF) and renders correlated, continuous, and real-time measurements of the circulating drugs' pharmacokinetics. The μ NEAB-patch is created following an introduced low-cost fabrication scheme, which transforms a shortened clinical-grade needle into a high-quality gold nanoparticle-based substrate for robust aptamer immobilization and efficient electrochemical signal retrieval. This enables the reliable in vivo detection of a wide library of ISF analytes—especially those with nonexistent natural recognition elements. Accordingly, we developed μ NEABs targeting various drugs, including antibiotics with narrow therapeutic windows (tobramycin and vancomycin). Through in vivo animal studies, we demonstrated the strong correlation between the ISF/circulating drug levels and the device's potential clinical use for timely prediction of total drug exposure.

INTRODUCTION

To realize precision and personalized medicine for effective pharmacotherapy, the right drug needs to be delivered to the right patient at the right dose and at the right time. In that regard, appropriate dosing for pharmaceuticals that present narrow therapeutic windows, such as antibiotics, is particularly challenging. In such cases, the high inter/intrasubject variations—stemming from influential factors including kidney/liver function, tissue penetration, and drug-drug interactions—may often cause the drug level to fall outside the optimal therapeutic window. This can lead to adverse outcomes, such as kidney injury and ineffective pharmacotherapy.

To circumvent these issues, patients who are prescribed these medications undergo therapeutic drug monitoring (TDM) sessions. At present, standard practices for conducting TDM involve invasive blood draws, followed by labor-intensive and high-cost laboratory-based analysis (e.g., chromatography and immunoassay) to capture the drug circulating level at one or two time point(s) (Fig. 1A) (1). These limitations severely compromise the utility of TDM for optimal dosing in many aspects. First, the turnaround times for results

are prolonged (~24 hours) and, thus, inadequate to allow for timely intervention. Second, the poor temporal resolution of the measurements (mostly confined to a single-trough level measurement) inherently limits the accuracy of the current TDM approaches in terms of predicting the drug's highly complex pharmacokinetic (PK) characteristics [e.g., area under the curve (AUC)] (2). Third, because of their limited accessibility, TDM sessions are conducted at suboptimal rates over the course of treatment and subsequently fail to capture longitudinal variations in the drug's PK characteristics. This shortcoming is particularly critical for antibiotics-based treatments, where the antibiotic itself or the coadministered drugs can affect the drug clearance (e.g., due to the changes that they make to renal function) (3). Also applicable to antibiotics-based treatments, these acknowledged challenges contribute to emerging antibiotic resistance: not only because of inadequate dosing but also because of avoiding the use of the best choice of antibiotic due to the need for TDM and the fears of inducing toxicities (4).

Wearable biosensors targeting non/minimally invasively accessible biofluids can, in principle, address the limitations encountered in current TDM practices by enabling the seamless, continuous, and real-time measurement of the drug levels (Fig. 1B) (5–9). To this end, probing interstitial fluid (ISF) is a viable approach. A wide panel of pharmaceutical partitions into ISF with a high correlation to their circulating blood levels, many of which may not diffuse into other accessible biofluids such as sweat and saliva (10). Furthermore, probing ISF could be advantageous in the context of antibiotics-based treatments, given that the ISF compartment is often the intended site for drug activity, as it is in this space where many bacterial infections start and progress. In such cases, the ISF-based measurements may provide a more direct insight as compared to the blood-based counterpart (11).

The molecular information in the ISF can be minimally invasively retrieved with the aid of microneedle devices. These devices have sharp, mechanically robust, and short needle-like features that

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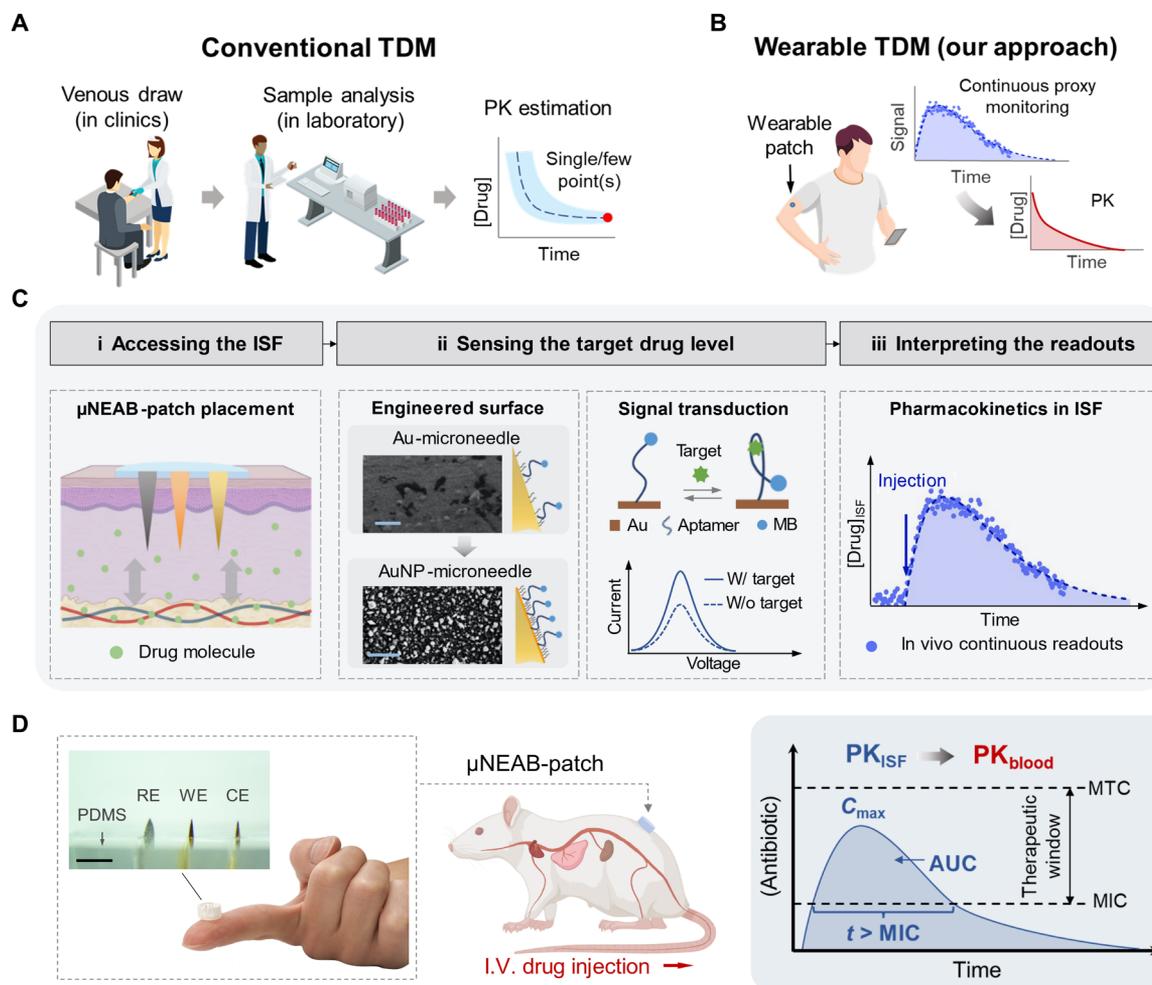


Fig. 1. μ NEAB-patch for wearable TDM. (A) Schematic illustration of the procedures involved in conventional TDM approaches. These approaches rely on venous blood draw in clinics followed by analysis in a centralized laboratory and render limited measurement(s) of the drug's circulating level to estimate the drug's PK. (B) Schematic illustration of the envisioned wearable TDM modality. A wearable patch tracks the drug level in interstitial fluid (ISF) continuously and in real time to infer the drug's PK. (C) Wearable TDM enabled by the μ NEAB-patch: (i) The drug molecules in the dermal ISF are minimally invasively accessed by the patch. (ii) The engineered AuNP-microneedle substrate renders reliable aptamer immobilization and efficient transduction of the target-aptamer binding events into voltammetric readouts. Insets show the scanning electron microscopy (SEM) images of bare and AuNP-microneedle electrode surfaces (scale bars, 5 μ m). (iii) In vivo continuous readouts are used to infer the drug's PK. (D) Left: Photos of an assembled μ NEAB-patch, consisting of microneedle electrodes embedded in an elastomeric substrate [polydimethylsiloxane (PDMS)]. WE, CE, and RE correspondingly denote working, counter, and reference electrodes. Scale bar, 2 mm. Middle: Schematic representation of a μ NEAB-patch applied in a rat model for in vivo TDM. Right: Utility of the μ NEAB-patch for inferring the PK characteristics of antibiotics. MTC and MIC denote minimally toxic and inhibitory concentrations, respectively. I.V., intravenous.

enable easy and fracture-free skin penetration with no/minimal pain. By coupling electrochemical sensing capability with the microneedle's skin piercing functionality, microneedle devices can be adapted for the sample-to-answer quantification of ISF analytes in-skin (6, 12–14). However, the demonstrated microneedle-based electrochemical sensors rely on enzymes or ionophores for analyte recognition, excluding a wide variety of drug molecules for which these recognition elements are not available.

In that regard, the use of aptamers, as artificially engineered recognition elements, can greatly expand the library of detectable analytes (15). Although aptamer-based microneedles have been previously demonstrated, they are mostly geared at drug delivery (16) or multistep sampling/ex vivo affinity-based sensing (17). The latter group does not have means for acquiring real-time in vivo

signals, and thus, they are incapable of charting the PK profile of the hypothetical target drugs accurately and providing timely and actionable feedback.

By immobilizing redox signal reporter-coupled aptamer molecules onto the surface of an electrode, an electrochemical aptamer biosensor (EAB) can be formed—which reversibly and in real-time transduces aptamer-target bindings into an electrically measurable signal (18, 19). Several EABs have been developed and adapted for the measurement of analytes in blood, illustrating the utility of this class of biosensors for complex biofluid analysis (18, 20, 21).

Toward reliable, real-time, and continuous ISF biomonitoring, augmenting microneedles with EAB interfaces remains nontrivial. To elaborate, for robust EAB-based sensing, a high-quality surface (e.g., gold) is needed to ensure the strong covalent binding of the

aptamer molecules (typically with the aid of an intermediary thiol group) and the efficient retrieval of the transduced signal (22). For the envisioned setting, the surface must be additionally resilient against the disruptive mechanical conditions involved in dermal applications (e.g., insertion-induced delamination) while satisfying electrochemical requirements (e.g., high sensitivity and anti-fouling) (23–25). Nevertheless, the most recent demonstrations of EAB microneedles suffer from poor signal-to-noise ratio (SNR) measurements and the degradation of the sensing layer during *in vivo* operation despite using complex and costly fabrication schemes (26).

Addressing these challenges, here, we present a simple and low-cost EAB-on-microneedle fabrication scheme to develop a microneedle-based EAB patch (“ μ NEAB-patch”) for in-skin ISF biomonitoring (Fig. 1C). Our fabrication scheme centers on engineering a robust gold nanoparticle (AuNP) coating via a single deposition step, which uniquely transforms the surface of a clinical-grade needle into a high-quality gold working electrode for strong aptamer immobilization. Following this scheme, the sensing interfaces are built on the tip of shortened acupuncture gold needles, allowing to simultaneously leverage the needles’ high sharpness for skin penetration and conductivity for signal routing.

Illustrating the generalizability of our approach, we developed multiple μ NEABs targeting antibiotics (tobramycin and vancomycin) and other drugs (doxorubicin: an anticancer drug; thrombin: a procoagulant and anticoagulant). The antibiotic choice was motivated by noting their narrow therapeutic window (tobramycin: 4 to 21 μ M, 214 to 267 μ M·hour (AUC) (27); vancomycin: 6 to 35 μ M, 276 to 414 μ M·hour (AUC) (28)] and their high rate of treatment-induced kidney injuries [tobramycin: 12% (29); vancomycin: 24% (30)]. Note that such injury rate can be effectively minimized via advanced TDM solutions (2).

Our characterization results indicate that the developed μ NEABs present a high level of sensitivity and stability (comparable to EABs developed on standard gold electrodes) while being suitable for intradermal applications. The *in vivo* animal studies—which were performed with the tobramycin μ NEAB-patch on a rat model—revealed the high correlation of blood-ISF readings and the potential of real-time continuous ISF measurements for early prediction of critical circulating PK parameters that are commonly used to guide dosing (Fig. 1D). By reducing the feedback time for dosage adjustment from ~24 hours to minutes and obviating cumbersome and costly sample collection/analysis, our device serves as a viable yet accessible TDM solution to maximize safety and optimize pharmacotherapy outcomes.

RESULTS

To construct the μ NEAB-patch, we first fabricated microneedle electrodes by affixing clinical-grade acupuncture needles within a flexible polydimethylsiloxane (PDMS) substrate (fig. S1). This configuration leverages the needles’ robustness and sharpness to reliably and painlessly pierce the stratum corneum layer of the skin, making it suitable for accessing dermal ISF analytes (31). In addition, our mechanical characterization studies validated the high mechanical stability and robustness of the designed structure amid disruptive compression and shear forces relevant to the envisioned dermal application [fig. S2, A to C; performed following previously reported protocols (32, 33)].

To render real-time and continuous sensing, pharmaceutical-targeting aptamers are immobilized onto the microneedle electrode surface. The distal ends of the aptamers are tagged with redox-active molecules [methylene blue (MB)] as signal reporters. The aptamers undergo reversible (18, 19) and rapid [in millisecond scales (34)] conformational changes upon binding to the target pharmaceutical. The aptamer conformational change alters the charge transfer rate between the signal reporter and electrode surface, which can be measured via voltammetry-based approaches.

As a key fabrication step of the μ NEAB-patch, we specifically engineered a low-cost AuNP-coated gold microneedle surface (denoted as AuNP-microneedle) to serve as the biosensor substrate. This coating is critical to the EAB construction and signal transduction. It minimizes substrate impurity (which comes hand in hand with the microneedle’s low cost) and renders a high-quality surface for strong aptamer binding (via a self-assembled thiol group) (35, 36). Its nanostructured morphology effectively increases the area for aptamer immobilization, which is useful for increasing the SNR of measurements (37, 38). In addition, it secures a strong adhesion to the microneedle substrate (owing to the local galvanic reduction of gold ions during the electrodeposition) (39, 40), enabling device resilience against disruptive mechanical forces encountered in dermal settings (e.g., during insertion).

The surface chemistry of the AuNP-microneedle was first characterized and compared with that of the bare microneedle substrate (originally Au-plated). As shown in the scanning electron microscopy–energy-dispersive spectroscopy (SEM-EDS; Fig. 2A), a high level of nickel (Ni) impurity was identified on a bare microneedle surface, while the AuNP coating effectively suppressed the Ni-associated peaks. Eliminating the Ni exposure is important, because Ni and its associated surface oxide layer can impede aptamer immobilization for signal retrieval (fig. S3). To further verify this point, representative tobramycin μ NEABs were constructed on both substrates, and the biosensors’ voltammetric readouts were recorded in a custom developed artificial ISF buffer environment. As shown in Fig. 2Bii, for an AuNP-coated μ NEAB, a well-defined MB reduction peak with a flat baseline was observed, indicating the formation of a compact self-assembled monolayer (41). However, for the bare microneedle electrode, the voltammetric peak of the signal reporter is hardly differentiated from the background (Fig. 2Bi). As shown in fig. S4, the comparison of the readouts of AuNP-deposited microneedle biosensors with Au-evaporated equivalents demonstrates the benefit of the AuNP coating in terms of enhancing the signal current, which is important for increasing the measurements’ SNR and precision (37, 38).

To illustrate the generalizability of our approach, we developed additional microneedle-based EABs (targeting vancomycin, doxorubicin, and thrombin; in addition to tobramycin) by immobilizing the corresponding aptamers on the AuNP-microneedle substrates. As shown in Fig. 2 (C and D) and fig. S5, for all four cases, the corresponding biosensor responses and analyte concentrations present a monotonic relationship with minimal interdevice variations. Here, relative peak current change was used to represent the sensor response to minimize interdevice variations (42).

Aligned with our aforementioned motivation of tobramycin PK monitoring, in the subsequent characterization experiments, we primarily focused on tobramycin sensing. Accordingly, we first compared the performance of the tobramycin μ NEAB with the tobramycin-EAB constructed on a standard gold disc electrode and

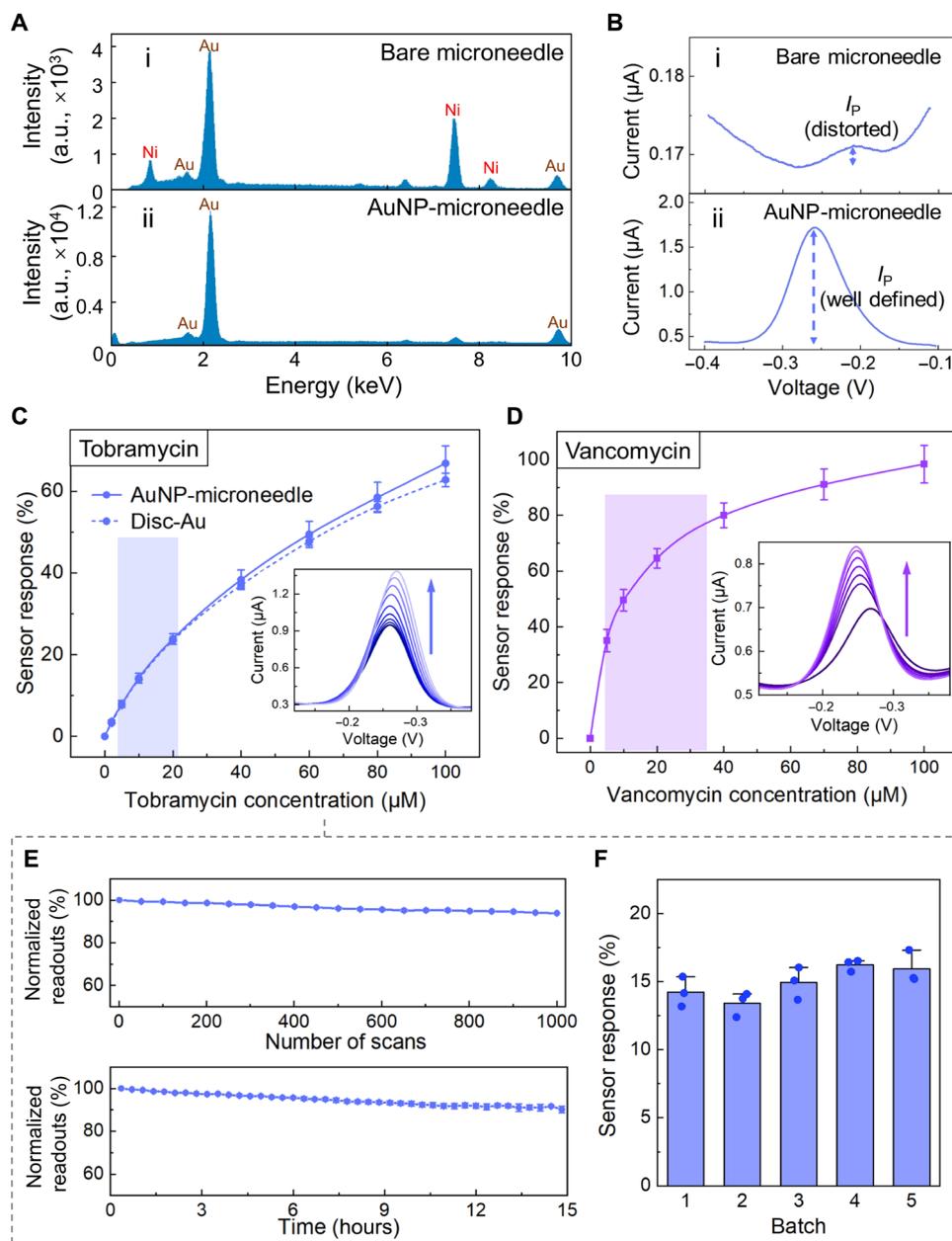


Fig. 2. Development and characterization of μNEABs . (A) Energy-dispersive spectroscopy (EDS) spectrum of a bare microneedle surface (i) and an AuNP-microneedle surface (ii). a.u., arbitrary units. (B) Square wave voltammograms of μNEABs constructed on bare microneedle (i) and AuNP-microneedle (ii) substrates. (C) Response of tobramycin μNEABs , in comparison with tobramycin EABs constructed on gold disc electrodes. Error bars indicate SDs ($n = 5$). Inset shows the square wave voltammograms acquired from a μNEAB with 0, 2, 5, 10, 20, 40, 60, 80, and 100 μM tobramycin (arrow indicates the increase of concentration). (D) Response of vancomycin μNEABs . Error bars indicate SDs ($n = 5$). Inset shows the corresponding square wave voltammograms with 0, 5, 10, 20, 40, 70, and 100 μM vancomycin (arrow indicates the increase of concentration). The shaded area in (C) and (D) indicates the target therapeutic window for the respective drug. (E) Normalized tobramycin μNEAB readout variations under repetitive interrogation (top) and with extended operation time (bottom). Error bars indicate SDs ($n = 3$). (F) Tobramycin μNEABs ' response to 10 μM tobramycin. Three sensors were characterized for each batch. Error bars indicate SDs. All the experiments were performed in artificial ISF buffer solutions.

found that the two have similar sensitivity levels (Fig. 2C and fig. S6A). To verify that the tobramycin μNEAB 's electrochemical response originates from the binding of the target molecules to MB-tagged aptamers, we conducted a control study using aptamer-free devices and additionally used electrochemical impedance spectroscopy (43) to characterize the μNEAB 's response (fig. S6, B to D). We

also characterized our μNEAB 's response to an increasing/decreasing target concentration and demonstrated the μNEAB 's rapid and reversible sensing capability [fig. S7A; in line with previously reported results (19)]. Moreover, we studied the μNEAB 's selectivity against relevant interfering species. Figure S7 (B and C) shows that the tested biosensors' responses are minimally affected (<5%) by the

presence of common endogenous molecules and frequently coadministered drugs [here, ibuprofen and azithromycin; also relevant to vancomycin monitoring (44–47)].

Furthermore, we characterized the tobramycin μ NEAB from the standpoint of long-term stability and reproducibility. To investigate the biosensor's long-term stability, we recorded its baseline readout in an artificial ISF buffer under two extreme scenarios: repeated interrogation (1000 scans) and extended operation time (>15 hours). In both scenarios, the biosensor readouts presented <10% drift (Fig. 2E), indicating that both the electrochemically driven and time-dependent desorption of the self-assembled monolayer were minimal. Our characterization of different batches of the tobramycin μ NEABs yielded minimal inter/intrabatch response variations, demonstrating the high reproducibility of the biosensor fabrication scheme (Fig. 2F).

Toward translation into in vivo biomonitoring, we extended our device characterization by using ex vivo models that mimic the envisioned intradermal ISF biosensing scenario.

To evaluate the biosensor's continuous response, we used a phantom gel setup and the complete μ NEAB-patch [consisting of the tobramycin aptamer-immobilized working electrode, a silver/silver chloride (Ag/AgCl) reference electrode, and a gold counter electrode, all microneedle-based]. We specifically used three test gels prespiked with different tobramycin concentrations, collectively representing the analyte concentration variations in dermal ISF. We rotated through these test gels and recorded the response of the μ NEAB-patch continuously (with the device being inserted in the gels). As shown in Fig. 3A, the μ NEAB produced rapid (<1 min) as well as highly stable and reversible responses to tobramycin, suggesting its high suitability for continuous ISF biomonitoring in tissue-like environments.

Furthermore, we characterized the μ NEAB performance in terms of its biofouling resistance. Biofouling is a major challenge for in vivo biosensing as it can render biosensors (including EABs) unusable within a short period of time. For this characterization, we used two methods. The first method was based on characterizing the biosensor response in a protein-spiked buffer solution. For this study, to mimic the effect of large proteins, we followed a previously reported protocol (48) and spiked the artificial ISF buffer to contain bovine serum albumin (20 mg/ml; within the concentration range of common large proteins in the ISF). In this setting, the sensor exhibited a relatively small drift over ~14 hours (both in the presence and absence of the flow; fig. S8, A and B). The second method was based on characterizing the biosensor readout drift in a tissue environment, which was performed by continuously recording the biosensor readouts in a piece of rat or porcine skin. Figure 3Bi and fig. S8C show that the in-skin measurements stayed within ~80% of the initial measurement values for over 5 hours of operation [comparable to previously reported results in a similar context (49)]. Furthermore, comparison of the biosensor's response to tobramycin (10 μ M) before versus after the biofouling test revealed a statistically nonsignificant effect on the biosensor response ($P = 0.23$ in Fig. 3Bii; $P = 0.24$ in fig. S8C).

Collectively, the biofouling characterization results indicate the preserved biosensing functionality of the μ NEAB within the envisioned measurement time window [corresponding to the drug's time excursion in the circulation ~2 to 3 hours (50)]. Relevant to these experiments, we also verified the μ NEAB's preserved signal transduction in surrounding skin by measuring its electrochemical impedance phase response in excised porcine skins, which were presoaked with tobramycin (fig. S6D). To further minimize drift

and enable accurate readouts, the effect of confounders that may alter the EAB performance needs to be systematically characterized [e.g., pH, ionic strength, surface adsorption of cells and biomolecules, and change of aptamer's binding kinetics in the tissue environment (22, 51)].

In addition, we evaluated the influence of insertion-induced disruptions to the biosensor performance. Previous studies performed with microneedle-based biosensors indicated a substantial degradation of the sensing layer upon insertion into the epidermis (26, 52). To characterize this effect in our context, we measured and compared the biosensor response to tobramycin (10 μ M) before and after repetitive insertions into a piece of porcine skin. As shown in Fig. 3C, the response remained relatively constant (<10% variations), indicating the robustness of the coated/immobilized layers against insertion-induced disruptions. For comparison, we performed similar characterization studies using equivalent microneedle devices with Au-evaporated (instead of AuNP-deposited) metallic coating [as conventionally pursued in the fabrication of microneedle biosensors (26, 32)]. Figure S9 shows that the readouts of the Au-evaporated microneedles were markedly reduced and that the devices completely lost their sensing functionality within a few insertions (attributable to the delamination of the evaporated gold coating). Furthermore, relevant to the envisioned dermal application, we characterized the stability of the μ NEAB-patch readout in the presence of motion, which may cause device delamination and signal distortion. As shown in fig. S2D, we observed negligible fluctuations in the patch readouts (<4%), despite the induced motion.

Moreover, we investigated the μ NEAB-patch's skin penetration capability. Figure 3D and fig. S10A show the hematoxylin and eosin (H&E)-stained rat skin tissue after microneedle insertion, confirming that the developed microneedle device penetrated the epidermis and accessed the dermal layer of the skin. The difference between the observed insertion depth and the physical length of the devised microneedle can be attributed to the deformation of the surface of the viscoelastic skin and manual error in cutting the skin during the section processing (53).

We also evaluated the biocompatibility of the μ NEAB-patch. We first assessed the possibility of cell toxicity, stemming from the potential leaching of the needles' substances (e.g., AuNP and Ag/AgCl) into the surrounding medium. Accordingly, we cultured human dermal fibroblasts (HDFs) in the medium that was originally incubated with the microneedle electrode and then performed a trypan blue exclusion assay. As shown in Fig. 3E, the viability of the cells in the experiment groups (cells cultured in the medium incubated with the microneedle electrodes) presented statistically nonsignificant differences ($P > 0.12$) as compared to the respective control group (cells cultured in an untouched medium). In addition, no noticeable change in the shape of the cells was observed in all the experiments. Similarly, we verified that, when culturing the HDFs directly with the microneedle electrodes, the HDF growth was unaffected by the microneedle electrodes' presence/contact. As shown in fig. S11A, the HDFs near the electrodes maintained normal morphology, and no senescence was observable. Furthermore, to evaluate the μ NEAB-patch's skin biocompatibility, we affixed our device onto the dorsal skin of a live rat for the duration of 3 hours before harvesting the skin tissue. Figure S11B shows the photo of the insertion point, alongside with the control skin (no microneedle insertion), where no morphological abnormality (e.g., swelling and increased number of immune cells) was observed. Collectively,

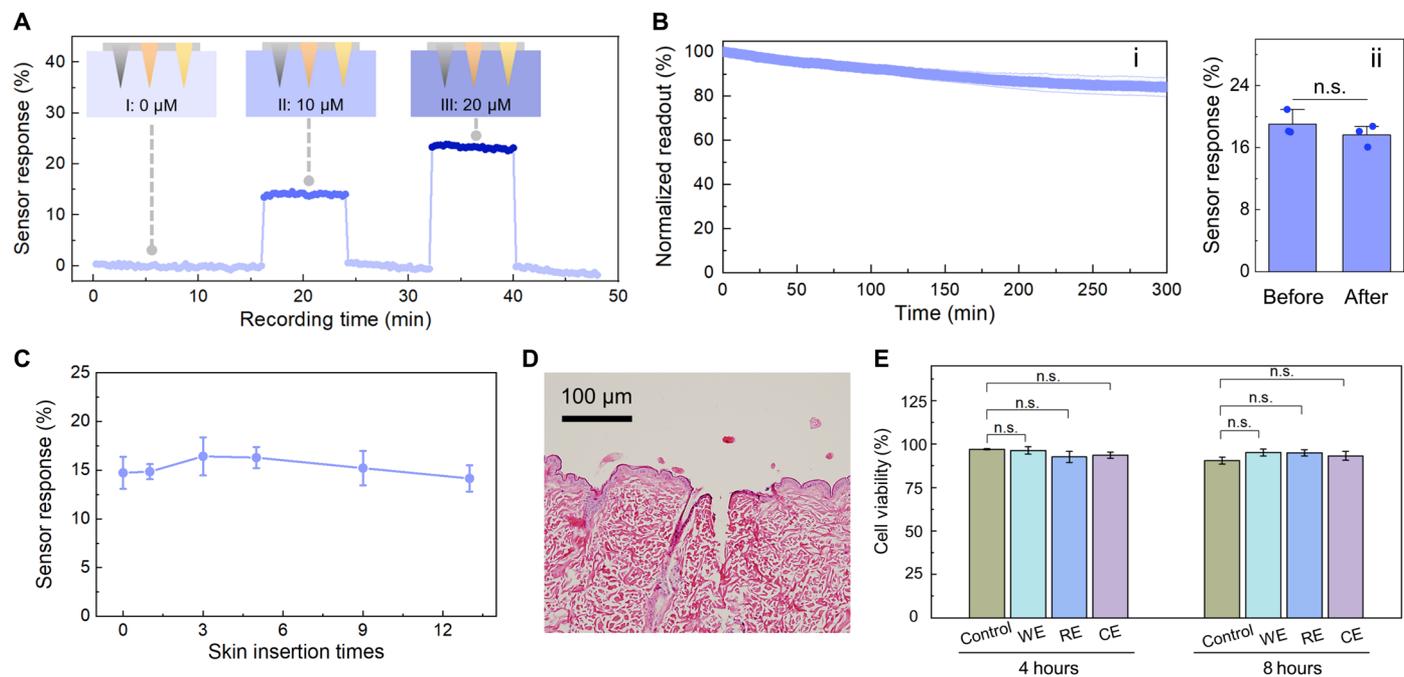


Fig. 3. Ex vivo μ NEAB-patch characterization. (A) Continuous measurements of μ NEAB-patch sensing response in a phantom gel setup. The μ NEAB-patch was inserted into three phantom gels in a rotational manner. Insets show the schematics of the testing setup. Tobramycin concentration levels in the three testing gels: 0, 10, and 20 μ M. (B) (i) Normalized continuous μ NEAB readouts in a hydrated rat skin tissue. (ii) Comparison of the μ NEABs' response to 10 μ M tobramycin before and \sim 300 min after skin tissue exposure. The error band/bars in (i)/(ii) indicate the SDs ($n = 3$). (C) μ NEAB responses to 10 μ M tobramycin before and after repetitive insertion into a porcine skin tissue. The error bars indicate the SD ($n = 4$). (D) Photo of hematoxylin and eosin (H&E)-stained rat skin showing the penetration of a devised microneedle electrode. (E) Viability of HDFs cultured with medium exposed to μ NEAB electrodes for 4 and 8 hours. The control result refers to the test performed using a blank matrix. The error bars indicate the SD of two biological and two technical replicates. "n.s." denotes statistical nonsignificance.

these results show no adverse effects on the cell/animal for the intended device operation time.

The developed μ NEAB-patch was then deployed in animal studies to monitor the PK profile of tobramycin in dermal ISF and investigate the drug's ISF-blood correlation. These experiments were performed on three healthy adult Sprague-Dawley rats. For these experiments, tobramycin was administered intravenously, while the rats were anesthetized, with the patch applied on their dorsal skin (Fig. 4A). Figure S10B shows no visible patch-induced bleeding and the rapid skin recovery upon the patch removal, reaffirming the minimally invasive nature of the developed technology.

To investigate the drug's ISF-blood correlation, blood samples were simultaneously collected before and at intermittent time points after the drug injection and then analyzed by the standard laboratory instrument [liquid chromatography with tandem mass spectrometry (LC-MS/MS)]. The ISF PK measurements were interpreted with the aid of a two-compartment PK model that accounts for the drug distribution (from blood to ISF) and elimination (Fig. 4B). We investigated the relationship between the drug's circulating AUC (AUC_{blood}) and the processed μ NEAB-patch readouts—specifically, the AUC (AUC_{ISF}) and the maximal value of the sensor responses (R_{max}). The choice of AUC_{blood} was motivated by its common use (as a standard measure of total drug exposure) to guide dosing (27).

We first assessed the μ NEAB-patch's core capability of tracking the ISF PK profile in vivo. As shown in fig. S12A, upon a bolus tobramycin injection (20 mg/kg), a rapid increase followed by a gradual

decrease in sensor readout was observed, corresponding to the drug's distribution and redistribution/elimination phases. In a separate vehicle control experiment, the injection of a similar amount of saline (vehicle of the drug) did not induce noticeable AUC_{ISF} (fig. S12B; $AUC_{\text{ISF}} = 0.099\%$ -hour, within 80 min after injection). The results suggest that the injection event and the long-term anesthesia have minimal confounding effects on the sensor response. To assess the generalizability of our solution for in vivo biomonitoring, we performed a proof-of-concept vancomycin biomonitoring experiment using the respective μ NEAB-patch. The captured vancomycin profile in ISF (fig. S13) presented a similar drug distribution/elimination pattern as that observed in previously reported vancomycin studies, which were performed via manual ISF sampling and off-body analysis (54).

Next, we extended the study to investigate the tobramycin's PK characteristics in relation to the administered drug dosages (performed on three rats). For each rat, we performed the associated experiments with at least 1 week interval to avoid carryover effects. As shown in Fig. 4C and figs. S14 and S15, both R_{max} and AUC_{ISF} increased with the increase of drug dosages for all three animals. Through analysis of blood samples, we found out that this trend was also reflected by the AUC_{blood} (Fig. 4D and fig. S15, B to D).

Figure 4E tabulates the collective results obtained from a total of nine independent trials (performed on three rats). It should be noted that, for the same animal, neither the blood-based nor the ISF-based drug measurements were linearly proportional to the correspondingly administered dosage. Furthermore, the animals'

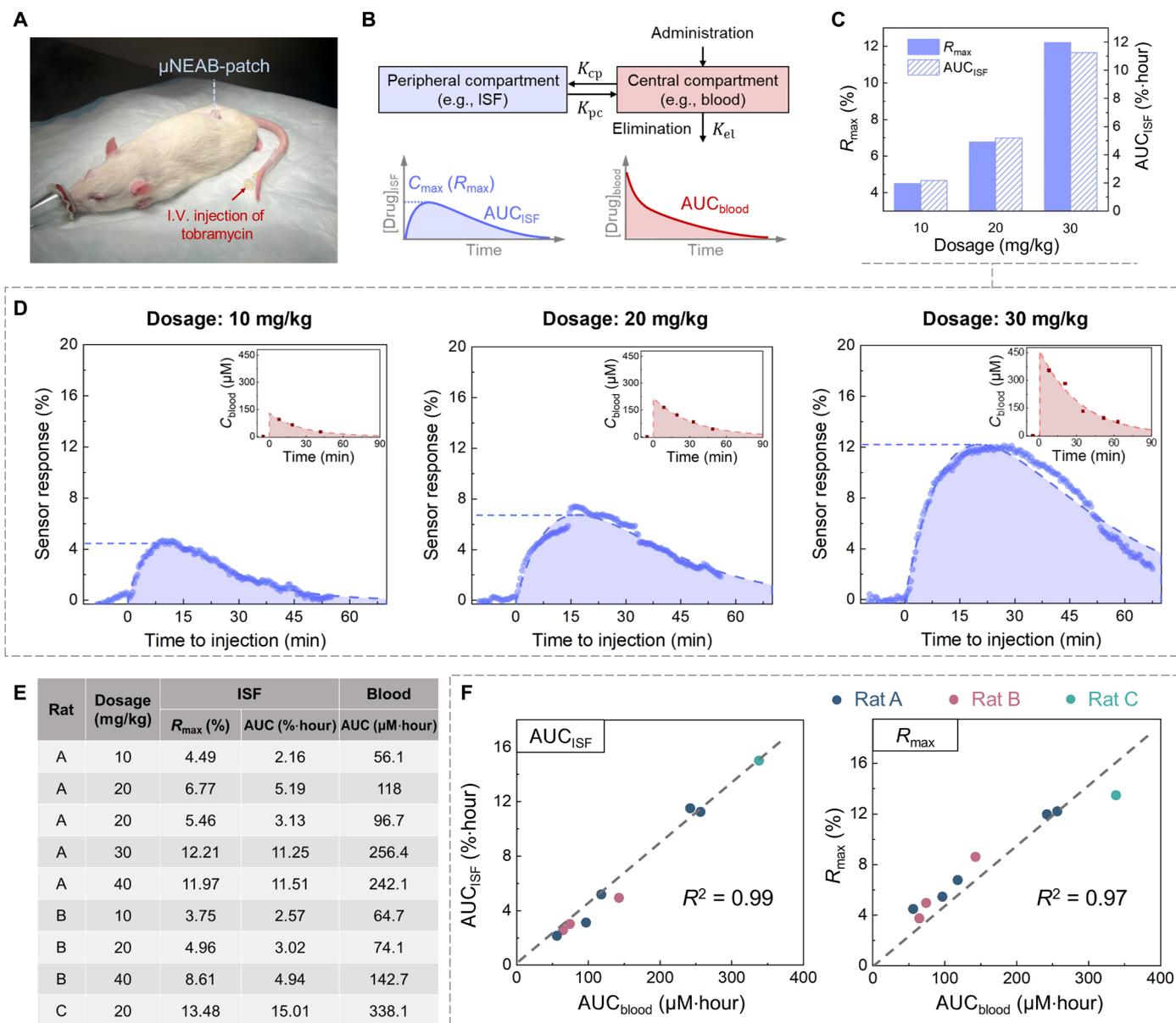


Fig. 4. In vivo ISF correlation studies enabled by the μNEAB -patch. (A) Photo of the animal study setup. The μNEAB -patch was applied at the back of the rat, and the drug was injected intravenously from the tail vein with the aid of a catheter. (B) Schematics of a two-compartment PK model and representative PK profiles in central and peripheral compartments. K_{cp} , K_{pc} , and K_{el} denote the first-order rate constants for distribution, redistribution, and elimination, respectively. (C) ISF PK parameters of one animal (rat A) with three different tobramycin doses. (D) The measured and baseline-corrected μNEAB -patch readouts of (C). Insets show the corresponding blood measurements. Dash lines show the fitted PK curves. (E) Tabulated PK results among three animals (nine trials). (F) Correlations between PK parameters in ISF and blood. Left: $\text{AUC}_{\text{blood}}$ versus AUC_{ISF} ; right: $\text{AUC}_{\text{blood}}$ versus R_{max} .

response to the same injection dosage (e.g., 20 mg/kg) varied substantially ($\text{AUC}_{\text{blood}}$: $180 \pm 112 \mu\text{M}\cdot\text{hour}$; AUC_{ISF} : $7.7 \pm 6.2\% \cdot \text{hour}$). These observations indicate high degrees of inter/intrasubject variations [in line with previously reported blood-based results (55)], which can be attributed to variations in the rats' underlying physiological conditions (e.g., renal function, weight, and diet) (3, 56).

Encouragingly, despite these variations, the μNEAB -patch-generated ISF readouts captured the circulating PK characteristics reliably. Figure 4F shows the high level of correlation between $\text{AUC}_{\text{blood}}$

and AUC_{ISF} [coefficient of determination (R^2) = 0.99] as well as $\text{AUC}_{\text{blood}}$ and R_{max} (R^2 = 0.97). These results suggest that the real-time continuous ISF readings rendered by our μNEAB -patch can be leveraged to predict the subject's total drug exposure for precision dosing (albeit it must be noted the prediction error for R_{max} increases at higher concentrations). The corresponding Bland-Altman plots for these measurements are shown in fig. S16 (A and B). Specifically, when the maximum response value is used, the feedback time can be reduced to ~ 15 min (fig. S16C). This provides the possibility of

finetuning the dosage within the intended therapeutic window and/or the time interval to next dosing administration.

DISCUSSION

The ex vivo and in vivo characterization results comprehensively support the suitability of the μ NEAB-patch for tracking the drug's PK minimally invasively and in real time. The μ NEAB-patch renders high SNR measurements over prolonged in vivo operations. This is achieved by uniquely leveraging the enabling features of the AuNP coating that facilitates a strong adhesion to the microneedle substrate and an increased area for aptamer immobilization. The AuNP coating is realized by an introduced fabrication scheme, which transforms a widely used clinically grade needle (optimized for dermal application) into a high quality in vivo biosensor, while only requiring a simple deposition step, with an added cost of a few cents (table S1; total device material cost of ~\$2). These enabling attributes of the devised fabrication scheme allow for simultaneously overcoming the limitations of previous microneedle biosensors and minimizing the barriers to clinical translation, mass production, and eventual large-scale deployment/adoption of the device (10, 23).

The continuous ISF analyte readouts rendered by this patch revealed the high correlation of AUC_{ISF} and R_{max} with respect to the animal's total drug exposure. These results demonstrate the potential clinical utility of our solution for precision dosing. In particular, the use of R_{max} as an indicator of drug exposure, could be of tremendous value. It reduces the time for extracting the drug's circulating PK from several hours (time to trough: ~12 hours; sample analysis: ~6 to 12 hours) to minutes. In this way, the presented technology uniquely enables timely feedback for dosage adjustment and other interventions such as extending the time interval for dosing. This will effectively maximize the treatment efficacy while minimizing toxicities and adverse effects. It is also worth highlighting the large inter/intrasubject variations observed in the antibiotics' circulating PK (similar to previous findings). These observations further emphasize the pressing need for performing TDM at a higher frequency and with an improved accuracy, aligned with the possibilities offered by our technology.

Toward translating this technology into clinical settings, dedicated engineering and clinical efforts are needed. While here we mainly focused on studying the performance of the developed tobramycin μ NEAB, additional engineering efforts are needed to evaluate and optimize the in vivo performance of the other μ NEABs (e.g., vancomycin) that are introduced in this work. Furthermore, existing commercial wearable packaging/system integration solutions can be adopted to form a fully integrated wireless patch, given that our patch is compact (~6 mm in diameter) and light (0.5 g) and, in principle, requires the same grade of electronics for wireless operation as those used in commercial solutions (e.g., continuous glucose monitoring devices). The technology could particularly benefit from surface engineering methods (49), differential/auxiliary measurement techniques (18), and corrective algorithms that minimize error caused by ISF-specific confounding factors (e.g., biofouling-induced drift within a tissue environment). Furthermore, standard microneedle sensor calibration methodologies are needed to benchmark the biosensor performance in the ISF environment. To this end, the findings from recently introduced ISF analyte sampling/analysis techniques are insightful and have formed a solid foundation for building these methodologies (6, 10, 57). Moreover, large-scale

clinical studies are needed to assess the ISF-blood correlation across different patient populations. These studies could benefit from advanced machine learning algorithms and data analytics approaches that render personalized models for precision dosing (1, 27).

The convergence of these efforts can establish an unprecedented wearable TDM modality. This modality directly addresses the problem of inappropriate drug dosing, which is a major cause of complications in antibiotics-based treatments. For tobramycin and vancomycin alone, these complications cause >40,000 acute kidney injuries and >\$5 billion treatment cost per year in the United States (2, 30). Recent studies have estimated that improvements in the accuracy of the used TDM methods can reduce these adverse outcomes by threefold (2). In addition, the availability of a more practical TDM platform could also facilitate the access to drug regimens with higher chances of efficacy as opposed to the selection of alternative agents. The latter approach is often used in current medical practice to avoid the demands of TDM but, at the same time, brings higher chances of failure and possibility of inducing antibiotic resistance (in the case of antibiotics). Therefore, we anticipate that the optimization and adoption of our technology can greatly promote enhanced pharmacotherapy outcomes with consequent improvements in the quality of life for large groups of patients and substantial savings in health care costs. Furthermore, the presented technology can be adapted to monitor a wide range of clinically informative analytes (e.g., markers of disease and well-being). Thus, it can be broadly applied in a variety of biomonitoring settings (e.g., ISF biomarker investigations, large-scale clinical trials, and telehealth) and for various biomedical applications to advance personalized and precision medicine.

MATERIALS AND METHODS

Materials and reagents

All reagents were purchased from Sigma-Aldrich (MO, USA) unless stated. Tris(2-carboxyethyl)phosphine hydrochloride (TCEP) was purchased from TCI America Inc. (OR, USA). The human α -thrombin was purchased from Haematologic Technologies Inc. (VT, USA). Tobramycin (900 μ g/mg) and phosphate-buffered saline (PBS; 1 \times , pH 7.2; Gibco) were purchased from Thermo Fisher Scientific (MA, USA). Tobramycin and vancomycin aptamers were purchased from Integrated DNA Technologies Inc. (IA, USA), and doxorubicin and thrombin aptamers were purchased from Biosearch Technologies Inc. (CA, USA). PDMS (Sylgard 184 Silicone Elastomer) was purchased from Dow Corning (MI, USA). Gold-plated acupuncture needles were purchased from Suzhou Acupuncture and Moxibustion Appliance Co. Ltd. (Suzhou, China). The lancets (30 gauge) were purchased from CVS Pharmacy (RI, USA). Disc gold electrodes (diameter: 1.6 mm) were purchased from Bioanalytical Systems Inc. (IN, USA). Ag/AgCl ink was purchased from Ercon Incorporated (MA, USA).

μ NEAB-patch fabrication

The μ NEAB-patch consists of three repurposed microneedle electrodes, a PDMS substrate, and a three-dimensionally (3D) printed case (as the housing of the μ NEAB-patch). The PDMS substrate was fabricated by mixing the base and the curing agent at a 10:1 ratio. The mixture was subsequently poured into a petri dish (thickness: ~3 mm) and cured at 70°C for 5 hours. The cured PDMS was then cut and embedded within the cylindrical 3D printed case

(diameter: 6 mm; height: 5 mm). The solid needles were inserted into the PDMS substrate with the aid of a custom-designed mold to form a microneedle-based three-electrode configuration (exposed tip length: ~1 mm; base diameter: 350 μm ; separation between electrodes: ~2 mm). Flexible wires were used and soldered to the distal end of the microneedle electrodes to establish connection with the potentiostat. The whole device was sealed by epoxy.

The working and counter electrodes were constructed using gold-plated acupuncture needles. The needles were cleaned by sonication in ethanol followed by deionized (DI) water (5 min for each solvent). To form an AuNP-microneedle, the microneedle electrode was immersed in a stirring solution containing chloroauric acid (1.2 mg/ml), 0.1 M sodium chloride (NaCl), and 1.5 weight % (wt %) hydrochloric acid. A 30-ml volume of the prepared solution can be used to coat about 100 microneedles. A pulsed waveform of 0 and -0.4 V (versus Ag/AgCl) was applied for 120 cycles (one cycle: 1 s for each potential) to form an AuNP coating. A bare microneedle (with an originally Au-plated surface) was directly used as a counter electrode. The reference electrode was constructed by dip-coating a lancet with Ag/AgCl ink (1:1 diluted in toluene) before inserting into the PDMS substrate.

Characterization of microneedle electrode surface morphologies and chemical compositions

The bare microneedle and AuNP-microneedle morphologies were characterized by SEM (ZEISS Supra 40VP). Surface chemical compositions were characterized by EDS (Thermo NORAN System 6). The size of the deposited AuNP was quantified by analyzing the SEM images using ImageJ (268 ± 56 nm).

Characterization of microneedle mechanical stability

The compression experiment of the microneedle device was performed in a universal testing machine (MultiTest 2.5-i, Mecmesin Ltd.) with a loading rate of 1 mm/min. The shear load experiment was performed using another universal testing machine (5966, Instron Inc.) with a loading rate of 0.5 mm/min. A 10-layer stacked parafilm was used to mimic the skin for the needle to puncture through (32). The loading and unloading data were recorded for both tests to show mechanical reversibility. The characterization of the device's structural stability against skin injection was performed by inserting the needle into a porcine skin for 20 times and measuring the needle's length with the aid of optical microscopy.

DNA aptamer sequences

The sequence of the aptamer probes used in the experiments are listed as follows:

tobramycin (5'-/5ThioMC6-D/GGGACTTGGTTTAGGTAATGAGTCCC/3MeBIN/-3') (55), vancomycin (5'-/5ThioMC6-D/CGAGGGTACCGCAATAGTACTTATTGTTCGCCTATTGTGGGTCGG/3MeBIN/-3') (21), doxorubicin (5'-/5ThioMC6-D/ACCATCTGTGTAAGGGGTAAGGGGTGGT/3MeBIN/-3') (19),

and thrombin (5'-/5ThioMC6-D/TAAGTTCATCTCCCCGGTTGGTGTGGTTGGT/3MeBIN/-3') (58).

EAB fabrication

To fabricate EABs, a 5- μl aliquot of the 100 μM aptamer stock solution was thawed to room temperature and then reduced for 1 hour in the dark with 10 μl of TCEP solution. The TCEP solution was prepared in a tris buffer solution containing 100 mM tris hydrochloride,

140 mM NaCl, 20 mM magnesium chloride, and 20 mM potassium chloride (KCl). TCEP (100 mM) was used to fabricate doxorubicin EABs, while other EABs were fabricated with 10 mM TCEP (to achieve a lower probe density in the fabricated EABs). The TCEP-reduced aptamer was then diluted in 500 μl of PBS. To construct aptamer sensors on disc gold electrodes, the electrodes were electrochemically cleaned following the previously reported method (41). The cleaned disc electrodes or the freshly prepared microneedle electrodes were immersed in aptamer solution for 2 hours at room temperature in the dark. Following this, the sensors were immersed overnight at room temperature in 20 mM 6-mercapto-1-hexanol (MCH; prepared in PBS) to coat the remaining gold surface and to remove nonspecifically adsorbed aptamers. After this, the sensors were rinsed with DI water and stored in the artificial ISF buffer solution. To construct the control aptamer-free device, the freshly prepared AuNP-microneedle electrode was immersed in 20 mM MCH (prepared in PBS) overnight at room temperature, followed by rinse with DI water.

Ex vivo μNEAB characterization

All the electrochemical measurements were performed using a CHI660E or a CHI1040C electrochemical workstation (CH Instruments Inc., TX, USA). The ex vivo sensor characterizations were performed in an electrochemical cell (reference electrode: Ag/AgCl; counter electrode: platinum) containing artificial ISF buffer solution. The artificial ISF solution was prepared according to the previously reported composition (9). Here, 6.3 g of NaCl (107.7 mM), 0.26 g of KCl (3.5 mM), 0.17 g of calcium chloride (1.5 mM), 0.17 g of magnesium sulfate (0.7 mM), 2.2 g of sodium bicarbonate (26.2 mM), 0.26 g of monosodium phosphate (1.7 mM), and 2.1 g of sodium gluconate (9.6 mM) were mixed in 1 liter of DI water, and the pH was adjusted to 7.4. All sensors were interrogated using square wave voltammetry (SWV) with a frequency of ~200 Hz, a pulse amplitude of 25 mV, and a voltage increment of 1 mV. The acquired voltammograms were processed using MATLAB (MathWorks, MA, USA) [similar to a previously reported method (59)]. Specifically, to extract the voltammetric peak height information (which serves as our sensor readout), a linear baseline was first fitted to the corresponding local minimum current points at the 2 feet of the peak in the captured voltammogram. The peak current was extracted by subtracting the fitted baseline from the voltammogram and then sampling the resultant maximum value (e.g., as shown in fig. S4A).

For electrochemical impedance spectroscopy, the formal potential E_0 of the redox probe (i.e., MB) was first determined by cyclic voltammetry scanning (-0.1 to -0.45 V; scan rate: 100 mV/s) in the respective test matrix. E_0 was defined as the midpoint between the oxidation and reduction peaks of the voltammogram. The impedimetric measurement was then performed by setting the bias point to E_0 and applying an ac potential waveform of 10-mV amplitude (frequency range: 10 kHz to 1 Hz).

To construct the phantom gels, 1.4 wt % agarose powder (9) was mixed with artificial ISF solutions (containing tobramycin with various levels) and placed in an 80°C water bath. After agarose was completely dissolved, the solutions were cooled to room temperature to form phantom gels. The fabricated μNEAB -patch was inserted into the phantom gels, and the sensor was interrogated continuously (with the interrogation paused during μNEAB -patch transfer). To test the sensor drift in an ex vivo setting, the μNEABs were inserted

into an excised porcine skin (Stellen Medical, MN, USA), and the biosensor readouts were monitored continuously. The skin was placed at the bottom of a beaker containing artificial ISF solution to prevent dehydration. The skin insertion test was performed by placing the μ NEABs into an excised porcine skin followed by an immediate withdrawal (serving as one insertion). The biosensors' responses to tobramycin were tested in an electrochemical cell (containing artificial ISF buffer solution) before and after skin insertions.

To test the sensor/device stability in the presence of motion, a μ NEAB-patch was inserted into a piece of rat skin and attached to a vortex mixer (Thermo Fisher Scientific). The vortex mixer was adjusted to mimic 3D oscillatory acceleration conditions [$\sim 10 \text{ m/s}^2$ at $\sim 8 \text{ Hz}$, generated by the vortex mixer, following our previously reported wearable device characterization protocol (60)]. The μ NEAB-patch was connected to a potentiostat to continuously record its readout. The 3D acceleration data were measured by a smartphone.

Skin penetration efficiency test

The penetration test was performed on the rat skin immediately after the euthanasia of the animal (the carcass was donated by the Division of Laboratory Animal Medicine at University of California, Los Angeles, under a tissue sharing program to reduce the number of animals used). The hair on the lower back was removed by a depilation (Nair, Church & Dwight, NJ, USA) before the microneedle test was administered. The skin was penetrated multiple times with the developed microneedle, harvested, and fixed in 10% formalin (48 hours). The fixed skin was paraffin-embedded and sectioned. Sections ($4 \mu\text{m}$ in thickness) were collected every $20 \mu\text{m}$ throughout the sample and stained with H&E.

In vitro biocompatibility test

The cell toxicity test was performed using HDFs (61). The fabricated needle-based working, reference, and counter electrodes were separately incubated in three vials of Dulbecco's modified Eagle medium (DMEM; Thermo Fisher Scientific, MA, USA) in a CO_2 incubator (4 and 8 hours). The electrode incubation time is selected to span beyond the drug's half-life [~ 2 to 3 hours for tobramycin (50)]. After the incubation, the electrodes were removed, the resultant DMEM was mixed with serum (up to 10% fetal bovine serum) and the cells ($100,000$ cells per well), and the mixture was plated. The plated cells were incubated at 37°C in 5% CO_2 atmosphere (24 hours). After the incubation, all cells on the plate were collected by trypsinization. Cell viability was determined by trypan blue stain using the hemocytometer. Trypan blue is cell membrane impermeable and only enters cells with compromised membranes. Thus, the staining of a cell indicates its death (62). In a separate experiment, the microneedle electrodes and HDFs were placed on the bottom of the cell culture dish, the dish was plated with HDFs, and the images were taken after 24 and 48 hours.

Skin biocompatibility test

We performed the skin biocompatibility test by putting the animal (here, rat) under anesthesia and affixing the microneedle electrode array (5×5 microneedles) on the dorsal skin. The animal was then allowed free movement for 3 hours. Then, the microneedle electrode array was removed, and the animal was euthanized. The skin was collected immediately after the euthanasia and fixed in the 10% formalin. The fixed skin was paraffin-embedded and sectioned.

Sections ($4 \mu\text{m}$ in thickness) were collected every $40 \mu\text{m}$ and stained with H&E.

In vivo μ NEAB-patch characterization on a rat model

The animal study protocol was reviewed and approved by the Institutional Animal Care and Use Committee at the University of California, Los Angeles. Four adult female Sprague-Dawley rats were purchased from Charles River Laboratories International Inc. (MA, USA) (weight at the point of experiment: 300 to 400 g). Rats were housed in the facility (1 or 2 rats per cage) with controlled temperature and humidity on a 12-hour light/12-hour dark cycle with food and water available ad libitum throughout the studies. A minimal 7-day acclimate time was provided before any procedure was implemented.

In the drug monitoring experiment, the rat was under isoflurane anesthesia (1.5 to 2%) with a circulating heating pad to maintain its body temperature at $\sim 37^\circ\text{C}$. A peripheral venous catheter was placed into the tail vein right after anesthesia to facilitate intravenous drug injection. A μ NEAB-patch was applied onto the rat's lower back (with hair removed), and a Tegaderm film (3M, MN, USA) was used to secure the device in place. The suitability of this film for interfacing wearable devices with skin has been demonstrated by numerous previous studies (60, 63). The μ NEAB-patch was connected to a potentiostat to provide real-time readouts. The biosensor was interrogated using the same method and parameters as the ex vivo experiments (with ~ 30 -s interval between measurements). The biosensor baseline was monitored for at least 1 hour before drug injection. Venous blood was collected from the tail vein or the lateral saphenous vein before and at intermittent time points after drug injection. Blood was left undisturbed at room temperature for 15 min and then centrifuged at $10,000 \text{ rpm}$ for 10 min. The supernatant (serum) was stored at -20°C before analysis. To administer the tobramycin, the tobramycin stock solution (40 mg/ml ; Baxter International, IL, USA) was diluted with saline (Hospira, IL, USA) to a final volume of $\sim 1 \text{ ml}$ and slowly injected into the vein via the catheter. Similarly, to administer the vancomycin, the lyophilized vancomycin hydrochloride (1 g per vial; Almaject Inc., NJ, USA) was mixed with saline to form a clear solution (100 mg/ml) and injected into the vein via catheter.

Data analysis for in vivo experiments

In vivo experiment data were analyzed using MATLAB. First, the MB redox peak currents were extracted from recorded voltammograms using the same method as the ex vivo experiments. Continuous sensor readout $I_{\text{readout}}(t)$ was subsequently constructed. To correct for the sensor baseline drift, a hypothetical baseline $I_{\text{baseline}}(t)$ was constructed using an exponential equation [previously used to describe the EAB readout drift pattern in biofluid (51)]. The baseline was fitted using the preinjection sensor readouts, while ensuring that all the postinjection readouts were above the fitted baseline. The sensor response $r(t)$ was defined as

$$r(t) = \frac{I_{\text{readout}}(t) - I_{\text{baseline}}(t)}{I_{\text{baseline}}(t)} \times 100\% \quad (1)$$

PK analysis

The PK analysis was performed on the basis of a two-compartment PK model (64). Accordingly, the continuously recorded sensor response was fitted using a biexponential equation derived from the model

$$C_{\text{ISF}} = X[e^{-\beta t} - e^{-\alpha t}] \quad (2)$$

where α and β are related to the distribution and elimination rates, respectively, and X is the preexponential factor. Applicable to our in vivo studies, in the context of intravenous bolus administration, it can be assumed that the drug concentration in blood immediately peaks upon injection as it is rapidly distributed and then gradually declines as the drug is eliminated (64). Here, because of the limited number of blood samples acquired per trial, the blood concentration versus time curve was fitted using a simplified exponential equation to avoid overfitting

$$C_{\text{blood}} = Y e^{-\gamma t} \quad (3)$$

where γ is predominantly determined by the drug elimination rate and Y is the preexponential factor. The AUC and R_{max} information were extracted from the fitted PK profiles. In case of the need for establishing the point-to-point correlation of ISF and blood readings and unifying the expressions (2) and (3), the consideration of the analyte blood-ISF transport delay may be necessary (65). To construct Bland-Altman plots, the $\text{AUC}_{\text{blood}}$ was predicted based on the AUC_{ISF} and R_{max} information derived from the μNEAB -patch readouts. The data from one trial were used to calibrate the remaining measurements.

Tobramycin quantification with LC-MS/MS

The tobramycin concentrations in the rat serum were quantified using LC-MS/MS with a multiple reaction monitoring (MRM) technique (55). Sisomicin sulfate was used as the internal standard (IS). For calibration, tobramycin stock solution was prepared in DI water at a concentration of 1 mg/ml. The stock solution was further diluted with DI water to obtain calibration standards at 0, 100, 200, 500, 1000, and 1500 ng/ml. The IS stock solution was prepared in DI water at a concentration of 1 mg/ml and was further diluted with water to 10 $\mu\text{g}/\text{ml}$. The rat serum samples (5 μl) were first diluted into 445 μl of DI water. Fifty microliters of IS (10 $\mu\text{g}/\text{ml}$) was then spiked into 450 μl of calibration standards or diluted serum samples (to reach a final IS concentration of 1 $\mu\text{g}/\text{ml}$). The resultant samples were mixed and vortexed with 500 μl of acetonitrile, followed by centrifugation at 14,800 rpm for 10 min. The supernatant (1 ml) was mixed and vortexed with 500 μl of dichloromethane, followed by centrifugation at 14,800 rpm for 10 min. Then, 400 μl of the supernatant was mixed and vortexed with 400 μl of DI water, followed by centrifugation at 14,800 rpm for 10 min. Last, 100 μl of the supernatant was transferred into an autosampler vial for tobramycin quantification.

For high-performance LC (HPLC) analysis, Agilent 1200 series HPLC (Agilent Technologies, CA, USA) equipped with HTS PAL autosampler (CTC Analytics, MN, USA) was coupled to an API 4000 triple quadrupole mass spectrometer (Sciex, ON, Canada) for MRM experiments. Chromatographic separation was realized by the InfinityLab Poroshell 120 EC-C18 (3.0 mm by 50 mm, 2.7 μm , Agilent Technologies). The mobile phases A and B were water and acetonitrile, respectively, both mixed with 10 mM heptafluorobutyric acid. The flow rate was set at 400 $\mu\text{l}/\text{min}$ with 3 min of equilibrium time. The gradient starts with increasing B from 5 to 90% in 4 min (0 to 4 min), then maintaining 90% B for 4 min (4 to 8 min), followed by decreasing B from 90 to 5% in 1 min (8 to 9 min), and lastly maintaining 5% B for 3 min (9 to 12 min). Sample vials were

maintained at 4°C in the autosampler tray. The sample (20 μl) was loaded onto the column each time. The MS/MS was operated in MRM mode recording the following mass/charge ratio transitions: 468.4 \rightarrow 163.2 for tobramycin and 448.3 \rightarrow 160.2 for sisomicin. The declustering potential, entrance potential, collision energy, and collision cell exit potential were optimized at 86, 10, 35, and 10 V, respectively, for tobramycin and at 76, 10, 29, and 10 V, respectively, for sisomicin.

SUPPLEMENTARY MATERIALS

Supplementary material for this article is available at <https://science.org/doi/10.1126/sciadv.abq4539>

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Wearable microneedle-based electrochemical aptamer biosensing for precision dosing of drugs with narrow therapeutic windows

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